

PHYS852 Quantum Mechanics II, Spring 2010  
HOMEWORK ASSIGNMENT 3

Topics covered: Unitary transformations, translation, rotation, vector operators

1. [25]**Symmetry:** A quantum system is said to possess a ‘symmetry’ if the Hamiltonian operator,  $H$ , is invariant under the associated transformation. In other words, if  $H' = H$ , where  $H' := U^\dagger H U$ .
  - (a) [5] Show that  $H' = H$  is equivalent to  $[H, U] = 0$
  - (b) [5] Any hermitian operator can be used to generate a unitary operator via  $U = e^{-iG\phi}$ , where  $G^\dagger = G$  is the ‘generator’ of the symmetry transformation, and  $\phi$  is a free parameter. Show that  $[H, G] = 0$  is necessary and sufficient for  $H$  to be symmetric under  $U$ .
  - (c) [5] Show that when  $[H, G] = 0$ , the probability distribution over the eigenvalues of  $G$  does not change in time. In QM this means that  $G$  is a ‘constant of motion’. Must a QM constant of motion have a well-defined value?
  - (d) [5] What operator is the ‘generator’ of translation? If a system possesses ‘translational symmetry’ what operator is a constant of motion?
  - (e) [5] Consider a particle described by the Hamiltonian

$$H = \frac{P^2}{2M} + V(X). \quad (1)$$

What operator is the generator of translation? Show that  $H$  has translational symmetry only if  $V(x) = V_0$ .

2. [25] Consider a system described by the Hamiltonian

$$H = \frac{P^2}{2M} + \frac{1}{2}M\omega^2 X^2 + MgX, \quad (2)$$

where  $g$  has units of acceleration.

- (a) [5] Show that  $U_T^\dagger(d)XU_T(d) = X + d$  and  $U_T^\dagger(d)PU_T(d) = P$ .
- (b) [5] Solve for  $d$  and  $E_0$  such that  $H' := U_T^\dagger(d)HU_T(d)$  satisfies

$$H' = E_0 + \frac{P^2}{2M} + \frac{1}{2}M\omega^2 X^2 \quad (3)$$

- (c) [5] Let  $|\phi'_n\rangle$ ,  $n = 0, 1, 2, \dots$  be the  $n^{\text{th}}$  eigenstate of  $H'$ , with corresponding eigenvalue  $E'_n$ . What are  $E'_n$  and  $\phi'_n(x) = \langle x|\phi'_n\rangle$ ?
  - (d) [5] Show that  $|\phi_n\rangle := U_T(d)|\phi'_n\rangle$  is an eigenstate of  $H$  with eigenvalue  $E_n$ . What is the relationship between  $E_n$  and  $E'_n$ ?
  - (e) [5] What is the relationship between  $\phi_n(x) := \langle x|\phi_n\rangle$  and  $\phi'_n(x)$ ? What is  $\phi_n(x)$ ?
3. [10] Show explicitly that the momentum operator of a particle  $\vec{P}$  is a vector operator with respect to rotation. Show that the operator  $P^2 = \vec{P} \cdot \vec{P}$  is invariant under rotation about any axis (hint: choose a coordinate system where the axis of rotation is the z-axis).

4. [40/35] Consider an infinitesimal rotation about an arbitrary axis, described by the unitary operator

$$U_R(\vec{\epsilon}) = e^{-\frac{i}{\hbar}\vec{L}\cdot\vec{\epsilon}} = 1 - \frac{i}{\hbar}L_1\epsilon_1 - \frac{i}{\hbar}L_2\epsilon_2 - \frac{i}{\hbar}L_3\epsilon_3. \quad (4)$$

where  $\vec{L} = \sum_j L_j \vec{e}_j$  and  $\vec{\epsilon} = \sum_j \epsilon_j \vec{e}_j$ , with  $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$  being a right-handed set of orthogonal unit vectors. Using this notation, the angular momentum components are given by  $L_j = \sum_{k,\ell} \epsilon_{j,k,\ell} R_k P_\ell$ , with  $\epsilon_{j,k,\ell}$  being the totally antisymmetric Levi-Cevita tensor,

$$\epsilon_{jkl} = \begin{cases} 0; & \text{any index repeated} \\ 1; & \text{cyclic permutations of } \{j, k, \ell\} = \{1, 2, 3\} \\ -1; & \text{cyclic permutations of } \{j, k, \ell\} = \{3, 2, 1\} \end{cases}. \quad (5)$$

The components of  $\vec{R}$  and  $\vec{P}$  satisfy the commutation relation  $[R_j, P_k] = i\hbar\delta_{j,k}$ .

- (a) [10] Evaluate  $R'_j = U_R^\dagger(\vec{\epsilon})R_jU_R(\vec{\epsilon})$  for each component of the position operator  $\vec{R} = \sum_j R_j \vec{e}_j$ , and use this to deduce the  $3 \times 3$  matrix,  $M(\vec{\epsilon})$  that rotates an ordinary vector by the infinitesimal angle  $\vec{\epsilon}$ .
- (b) [5] Show that  $M(-\vec{\epsilon}) = M^T(\vec{\epsilon})$ , then show that  $M^T(\vec{\epsilon}) = M^{-1}(\vec{\epsilon})$  by showing that  $M^T(\vec{\epsilon})M(\vec{\epsilon}) = I$ .
- (c) [5] Now consider a finite rotation by  $\vec{\delta} = \sum_j \delta_j \vec{e}_j$ , described by the  $3 \times 3$  matrix  $M(\vec{\delta})$ . Clearly we must have  $M(\vec{\delta}) = M^N(\vec{\delta}/N)$ . Take the limit as  $N \rightarrow \infty$ , and use your result to part (a) to show that we can put  $M(\vec{\delta})$  into the form:

$$M(\vec{\delta}) = \lim_{N \rightarrow \infty} \left( 1 - \frac{1}{N} \Lambda(\vec{\delta}) \right)^N = e^{-\Lambda(\vec{\delta})} \quad (6)$$

where  $\Lambda(\vec{\delta})$  is a  $3 \times 3$  antisymmetric matrix, whose components are given by  $\Lambda_{j,k}(\vec{\delta}) = \sum_\ell \epsilon_{j,k,\ell} \delta_\ell$ .

- (d) [5] Show that the eigenvalues of  $\Lambda(\vec{\delta})$  are  $\omega_0 = 0$ , and  $\omega_\pm = \pm i\delta$ , where  $\delta = |\vec{\delta}|$ .
- (e) Show that the eigenvectors of  $\Lambda(\vec{\delta})$  are

$$\vec{u}_0 = \frac{\vec{\delta}}{\delta} \quad (7)$$

$$\vec{u}_\pm = \frac{(\delta_1\delta_2 \pm i\delta\delta_3)\vec{e}_1 + (\delta_2^2 - \delta^2)\vec{e}_2 + (\delta_2\delta_3 \mp i\delta\delta_1)\vec{e}_3}{\sqrt{2\delta^2(\delta^2 - \delta_2^2)}} \quad (8)$$

- (f) [5] Based on your result to part (e), show that

$$M(\vec{\delta})\vec{V} = \vec{u}_0(\vec{u}_0 \cdot \vec{V}) + \vec{u}_- e^{i\delta}(\vec{u}_+ \cdot \vec{V}) + \vec{u}_+ e^{-i\delta}(\vec{u}_- \cdot \vec{V}) \quad (9)$$

where  $\vec{V}$  is an arbitrary vector.

- (g) [5+5 bonus] Based on your results to parts (e) and (f), show that

$$\vec{V}' = U_R^\dagger(\vec{\delta})\vec{V}U_R(\vec{\delta}) = M(\vec{\delta})\vec{V} = \frac{\vec{\delta}(\vec{\delta} \cdot \vec{V})}{\delta^2} + \left[ \vec{V} - \frac{\vec{\delta}(\vec{\delta} \cdot \vec{V})}{\delta^2} \right] \cos(\delta) + \frac{\vec{\delta} \times \vec{V}}{\delta} \sin(\delta) \quad (10)$$